

(An Autonomous Institution - AFFILIATED TO ANNA UNIVERSITY, CHENNAI) S.P.G.Chidambara Nadar - C.Nagammal Campus S.P.G.C.Nagar, K.Vellakulam - 625 701, (Near Virudhunagar), Madurai District.

B.E-MECHATRONICS ENGINEERING Regulation - 2020 AUTONOMOUS SYLLABUS CHOICE BASED CREDIT SYSTEM (CBCS) CURRICULUM AND SYLLABI (III & IV)

VISION:

To make the Department of Mechatronics Engineering the unique of its kind in the field of Research and Development towards Industrial Automation & Robotics.

MISSION:

To impart highly innovative and technical knowledge in Mechatronics Engineering to the urban and unreachable rural student folks through "Total Quality Education"

PROGRAM EDUCATION OBJECTIVES:

Educational objectives of the course Bachelor of Mechatronics Engineering programme can be divided into

PEO 1: Graduates will be able to apply their multi-disciplinary knowledge to formulate, design, develop and analyse Mechatronics Systems.

PEO 2: Graduates will be able to come up with solution for any real time problems in the field of Mechatronics Engineering and allied areas demanded by the Industry and Society.

PEO 3: Graduates will be able to get familiarized with economical issues in Mechatronics Engineering and work in multi-disciplinary teams with ethical code of conduct.

PROGRAM OUTCOMES:

After going through the four years of study, the Mechatronics Engineering graduates will have the ability to

| | Graduate Attribute | Programme Outcome |
|---|---------------------------|---|
| 1 | Engineering knowledge | Apply the knowledge of mathematics, science, |
| | | engineering fundamentals, and an engineering |
| | | specialization to the solution of complex engineering |
| | | problems |
| 2 | Problem analysis | Identify, formulate, review research literature, and |
| | | analyze complex engineering problems reaching |
| | | substantiated conclusions using first principles of |
| | | mathematics, natural sciences, and engineering |
| | | sciences |
| 3 | Design/development of | Design solutions for complex engineering problems and |
| | solutions | design system components or processes that meet the |
| | | specified needs with appropriate consideration for the |
| | | public health and safety, and the cultural, societal, and |
| | | environmental considerations. |
| 4 | Conduct investigations of | Use research-based knowledge and research methods |
| | complex problems | including design of experiments, analysis and |
| | | interpretation of data, and synthesis of the information |
| | | to provide valid conclusions |
| 5 | Modern tool usage | Create, select, and apply appropriate techniques, |
| | | resources, and modern engineering and IT tools |
| | | including prediction and modeling to complex |
| | | engineering activities with an understanding of the |
| | | limitations |
| 6 | The engineer and society | Apply reasoning informed by the contextual knowledge |
| | | to assess societal, health, safety, legal and cultural |
| | | issues and the consequent responsibilities relevant to |
| | | the professional engineering practice |
| 7 | Environment and | Understand the impact of the professional engineering |
| | sustainability | solutions in societal and environmental contexts, and |
| | | demonstrate the knowledge of, and need for |
| | | sustainable development. |

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| 8 | Ethics | Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering |
|----|--------------------------|--|
| | | practice. |
| 9 | Individual and team work | Function effectively as an individual, and as a member |
| | | or leader in diverse teams, and in multidisciplinary |
| | | settings |
| 10 | Communication | Communicate effectively on complex engineering |
| | | activities with the engineering community and with |
| | | society at large, such as, being able to comprehend and |
| | | write effective reports and design documentation, make |
| | | effective presentations, and give and receive clear |
| | | instructions. |
| 11 | Project management and | Demonstrate knowledge and understanding of the |
| | finance | engineering and management principles and apply |
| | | these to one's own work, as a member and leader in a |
| | | team, to manage projects and in multidisciplinary |
| | | environments |
| 12 | Life-long learning | Recognize the need for, and have the preparation and |
| | | ability to engage in independent and life-long learning in |
| | | the broadest context of technological change |

PROGRAMME SPECIFIC OUTCOMES (PSOs):

PSO1: Graduates will be able to design and develop cost effective Mechatronics systems by adopting multi-disciplinary skills in Design, Manufacturing, Automation and Electronics.

PSO2: Graduates will be able to apply their knowledge in sensors, drives, actuators, controls, mechanical design and modern software & hardware tools to develop systems for performing specified tasks.

PSO3: Graduates will be able to become Technocrats and Entrepreneurs, build the attitude of developing new concepts on emerging fields and pursuing higher studies.



(An Autonomous Institution - AFFILIATED TO ANNA UNIVERSITY, CHENNAI) S.P.G.Chidambara Nadar - C.Nagammal Campus S.P.G.C.Nagar, K.Vellakulam - 625 701, (Near Virudhunagar), Madurai District.

BE-MECHATRONICS ENGINEERING

Regulation - 2020

AUTONOMOUS SYLLABUS

CHOICE BASED CREDIT SYSTEM (CBCS)

CURRICULUM AND SYLLABI

(III & IV)

SEMESTER III

| SI. No. | COURSE CODE | COURSE TITLE | CATEGORY | PERIODS PER WEEK | | K | TOTAL CONTACT PERIODS | CREDITS |
|------------|---------------------|---|----------|------------------------|---|---|-----------------------------|---------|
| | | | | Ρ | | | | |
| THE | THEORY | | | | | | | |
| 1 | MA1373 | Transforms and Partial Differential Equations | BS | 3 | 1 | 0 | 4 | 4 |
| 2 | EC1371 | Digital Electronics | PC | 3 | 0 | 0 | 3 | 3 |
| 3 | MT1301 | Analog Devices and Circuits | PC | 3 | 0 | 0 | 3 | 3 |
| 4 | MT1302 | Fluid Mechanics and Thermal Sciences | PC | 3 | 0 | 0 | 3 | 3 |
| 5 | MT1303 | Solid Mechanics | PC | 3 | 0 | 0 | 3 | 3 |
| 6 | MT1306 | Electrical Circuits and Machines | ES | 3 | 0 | 0 | 3 | 3 |
| PRA | CTICAL | | | | | 1 | 1 | 1 |
| 7 | MT1311 | Solid and Fluid Mechanics Laboratory | PC | 0 | 0 | 4 | 4 | 2 |
| 8 | MT1316 | Electrical Circuits and Machines Laboratory | ES | 0 | 0 | 4 | 4 | 2 |
| 9 | HS1321 | Interpersonal Skills- Listening and Speaking | EE | 0 | 0 | 2 | 2 | 1 |
| | TOTAL 18 1 10 29 24 | | | | | | | |

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

SEMESTER IV

| | | PERIODS | | Ρ | ERIO | DS | | |
|-----|---------------------|----------------------|----------|---|------|----|---------|---------|
| SI. | COURSE | | CATECODY | | PER | | TOTAL | |
| No. | CODE | COURSE TITLE | CATEGORY | ١ | WEEK | | CONTACT | |
| | | | | L | Т | Ρ | PERIODS | CREDITS |
| THE | THEORY | | | | | | | 1 |
| | NAA 400 | Statistics and | DO | 3 | 1 | 0 | 4 | 4 |
| 1 | MA1402 | Numerical Methods | BS | 3 | 1 | 0 | 4 | 4 |
| 2 | EE1471 | Control Systems | PC | 3 | 0 | 0 | 3 | 3 |
| 2 | | Engineering | | 5 | 0 | 0 | 5 | 5 |
| 3 | ME1471 | Kinematics of | PC | 3 | 0 | 0 | 3 | 3 |
| 5 | | Machinery | FU | 5 | 0 | 0 | 5 | 5 |
| 4 | MT1401 | Manufacturing | PC | 3 | 0 | 0 | 3 | 3 |
| 4 | WIT 1401 | Technology | FU | 5 | 0 | 0 | 5 | 5 |
| 5 | MT1402 | Microprocessors | PC | 3 | 0 | 0 | 3 | 3 |
| 5 | WIT 1402 | and its Applications | FU | 5 | 0 | 0 | 5 | 5 |
| 6 | MT1403 | Sensors and | PC | 3 | 0 | 0 | 3 | 3 |
| 0 | MT 1403 | Instrumentation | FU | 5 | 0 | 0 | 5 | 5 |
| PR/ | CTICAL | I | 1 | | 1 | | | 1 |
| | | Manufacturing | | | | | | |
| 7 | MT1411 | Technology and | PC | 0 | 0 | 4 | 4 | 2 |
| | | Sensors Laboratory | | | | | | |
| | | Microprocessors | | | | | | |
| 8 | MT1412 | and its Applications | PC | 0 | 0 | 4 | 4 | 2 |
| | | Laboratory | | | | | | |
| | | Introduction to | | | | | | |
| 9 | HS1421 | Advanced Reading | EE | 0 | 0 | 2 | 2 | 1 |
| | | and Writing | | | | | | |
| | TOTAL 18 1 10 29 24 | | | | | | 24 | |

SEMESTER III

TRANSFORMATIONS AND PARTIAL DIFFERENTIAL EQUATIONS MA1373

OBJECTIVES

This course enables the students to

- To introduce the basic concepts of PDE used in solving partial differential Equations.
- To introduce Fourier series which plays a vital role in solving boundary value problems.
- To acquaint the students with Fourier transform and Z-transform techniques.

UNIT I PARTIAL DIFFERENTIAL EQUATIONS

Formation – Solutions of first order equations – Standard types and Equations reducible to standard types - Lagrange's Linear equation - Solution of linear equations of higher order with constant coefficients - Linear non-homogeneous partial differential equations.

UNIT II FOURIER SERIES

Dirichlet's conditions – General Fourier series – Odd and even functions – Half-range Sine and cosine series - Complex form of Fourier series - Parseval's identity - Harmonic Analysis.

UNIT III **APPLICATIONS OF PARTIAL DIFFERENTIAL EQUATION** 12

Classification of partial differential equations- Method of separation of variables - Solutions of one dimensional wave equation and one-dimensional heat equation – Steady state solution of two- dimensional heat equation – Fourier series solutions in cartesian coordinates.

UNIT IV FOURIER TRANSFORM

Fourier integral theorem – Fourier transform pair - Sine and cosine transforms – Properties – Transform of elementary functions – Convolution theorem – Parseval's identity.

UNIT V **Z – TRANSFORM AND DIFFERENCE EQUATIONS** 12

Z-transform – Elementary properties – Inverse Z-transform – Convolution theorem – Initial and final value theorems - Formation of difference equation - Solution of difference equation using Z - transform.

TOTAL: 60 PERIODS

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 1 | 0 | 4 |

12

6

COURSE OUTCOMES

At the end of the course, students will be able to

- CO1 Form the partial differential equations and solve them using various techniques.
- CO2 Find the Fourier constants and frame the Fourier series of periodic functions.
- CO3 Classify and solve the initial and boundary value problems such as wave and heat flow equation
- CO4 Compute the Fourier transforms of standard functions and learn the properties.
- CO5 Apply the techniques of Z- transform to get the solutions of differential Equations.

TEXTBOOKS

- 1. Erwin kreyszig, 2015, *Advanced Engineering Mathematics*, John Wiley & Sons, 10th Edition, New Delhi.
- 2. Grewal B,S, 2017, *Higher Engineering Mathematics*, Khanna Publishers, 44th Edition, New Delhi.

REFERENCES

- 1. Bali, N, Goyal, M, & Watkins C, 2009, *Advanced Engineering Mathematics*, Firewall Media (An imprint of Lakshmi Publications Pvt., Ltd.,), 7th Edition, New Delhi.
- Narayanan, S, Manicavachagom Pillay T, K&Ramanaiah, G ,1998, Advanced Mathematics for Engineering Students, Vol. II & III, S.Viswanathan Publishers Pvt. Ltd, Chennai.
- 3. Glyn James, 2011, *Advanced Modern Engineering Mathematics*, Pearson Education, 4 th Edition, New Delhi.
- 4. Peter V, O'Neil, 2012, *Advanced Engineering Mathematics*, Cengage Learning India Pvt., Ltd, 7 th Edition, New Delhi.
- 5. Ramana, 2010, B,V, *Higher Engineering Mathematics*, Tata McGraw Hill, 11th Reprint, New Delhi.

WEB REFERENCES

- 1. http://soaneemrana.org/onewebmedia/ADVANCED%20ENGINEERING%20MATHE MATICS%20BY%20ERWIN%20ERESZIG1.pdf
- 2. http://sv.20file.org/up1/692_0.pdf
- 3. http://www.scribd.com/document/462665493/B-V-Ramana-Higher-Engineering-Mathematics-McGraw-Hill-Education-2018-pdf

EC1371 DIGITAL ELECTRONICS

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

OBJECTIVES

This course enables the students to

- To provide the Digital fundamentals, Boolean algebra and its applications in digital systems
- To familiarize with the design of various combinational digital circuits using logic gates
- To introduce the analysis and design procedures for synchronous and asynchronous sequential circuits
- To explain the various semiconductor memories and related technology
- To introduce the electronic circuits involved in the making of logic gates

UNIT 1 DIGITAL FUNDAMENTALS

Review of Number systems - Logic gates - Boolean algebra - Boolean postulates and laws - De-Morgan's Theorem, Principle of Duality - Simplification using Boolean algebra - Canonical forms, Sum of product and Product of sum - Minimization using Karnaugh map - NAND and NOR Implementation.

UNIT 2 COMBINATIONAL CIRCUIT DESIGN

Realization of combinational logic using gates - Design of combinational circuits - Adder , Subtractor, Parallel adder / Subtractor, Carry look ahead adder, Magnitude Comparator, Code converters, Parity generator and checker, Encoder, Decoder, Multiplexer, Demultiplexer -Function realization using Multiplexer, Decoder.

UNIT 3 SEQUENTIAL CIRCUITS

Latches - Flip-Flops - SR, JK, D and T, Master Slave Flip Flops - Shift registers - SISO, SIPO, PISO, PIPO - Binary counters – Synchronous and asynchronous up/down counters, mod - N counter, Counters for random sequence - Johnson counter - Ring counter.

UNIT 4 SYNCHRONOUS CIRCUIT DESIGN

Design of Synchronous Sequential Circuits - State Table and State Diagram - Design of Mealy and Moore FSM - Overlapping & Non-overlapping Sequence detector - Hazards - Hazard free realization - Case study on Vending Machine FSM.

9

9

9

UNIT 5 LOGIC FAMILIES AND PROGRAMMABLE DEVICES

Introduction to Logic families – RTL, TTL, ECL and CMOS - Basic memory structure – ROM, PROM, EPROM, EEPROM - RAM – Static and dynamic RAM - Programmable Logic Devices – Programmable Logic Array (PLA), Programmable Array Logic (PAL) – Implementation of combinational logic circuits using PLA, PAL - FPGA - Basic Architecture.

TOTAL: 45 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to:

- CO1 Outline the Boolean functions and various minimization techniques.
- CO2 Illustrate the combinational circuits used to perform basic digital operations.
- CO3 Develop a synchronous/asynchronous counters and shift registers using sequential logic.
- CO4 Construct the synchronous sequential circuits with hazard and hazard free conditions.
- CO5 Interpret the different types of memories for the implementation of combinational logic circuits and various logic families.

TEXT BOOKS

1. M Morris Mano, M.D.C., 2017. *Digital design: with an introduction to the verilog HDL, VHDL, and system Verilog,* 6th Edition, Pearson Education.

REFERENCES

- 1. Charles H.Roth, 2013. *Fundamentals of Logic Design*, 6th Edition, Thomson Learning.
- 2. Wakerly J F, 2002. Digital Design: Principles and Practices, 2nd Ed., Prentice Hall.
- 3. D. D. Givone, 2003. Digital Principles and Design, Tata Mc-Graw Hill, New Delhi.
- 4. Thomas L. Floyd, 2011. *Digital Fundamentals*, 10th Edition, Pearson Education Inc.
- 5. Stephen Brown & Zvonko Vranesic, 2013, *Fundamentals of Digital Logic with Verilog Design*, Third Edition, McGraw-Hill Higher Education, New Delhi, India.

MT1301

ANALOG DEVICES AND CIRCUITS

OBJECTIVES

This course enables the students to

- To study the basic characteristics of Diodes, Transistors, Rectifiers and oscillators.
- To study characteristics; realize various Circuits using Op-Amp ICs.
- To understand the various functionalities of ICs and Waveform generators.
- To study the internal functional blocks of test and Measuring Instruments.
- To study the characteristics of various electronic display devices.

UNIT I ANALOG ELECTRONICS

Semiconductor Diodes –Bipolar Junction Transistor – Characteristics Rectifiers and Filters - Regulated Power Supply –Switching Power Supplies, Thermal Considerations - Feedback and power amplifiers - Oscillators: Colpitts oscillator, Hartley oscillator and Wien bridge oscillator

UNIT II OPERATIONAL AMPLIFIERS AND APPLICATIONS

Operational amplifiers – Principles, Specifications, characteristics and applications-. Arithmetic Operations, Integrator, Differentiator, Comparator, Schmitt Trigger, Instrumentation Amplifier, A/D & D/A converters.

UNIT III WAVEFORM GENERATORS AND ICs

Triangular, Saw tooth and Sine wave generators - Multivibrators - Function generator ICs – Timer ICs –Voltage regulator ICs: fixed, Adjustable and General purpose - V/F and F/V converters – Optocouplers

UNIT IV TEST AND MEASURING INSTRUMENTS

Measurement of voltage, current, frequency and power using Multi meters, oscilloscopes, recorders, data loggers, voltage-controlled oscillators, counters, analyzers and printers.

UNITV DISPLAY DEVICES

Introduction, Photo Luminescence, Cathode Luminescence, Electro Luminescence, Injection Luminescence, LED, Plasma Display, Liquid Crystal Displays, Touch Screens,

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

9

9

9

10

~

Numeric Displays, Photo transistor, Solar cell, CCD.

TOTAL: 45 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO1 Apply the various switching devices in electronic circuits.
- CO2 Apply Op-Amp application circuits for signal analysis.
- CO3 Design various Signal Generation, Voltage regulation circuits using ICs.
- CO4 Analyze various internal functional blocks of test & measurement devices.
- CO5 Comprehend the principles of various display devices.

TEXT BOOKS

- 1. Salivahanan S., Suresh kumar N. and Vallavaraj A.,2012, *Electronic Devices and Circuits*, Tata McGraw Hill publishing company, New Delhi, 3rd edition.
- 2. Roy Chowdhury D. and Jain Shail B., 2018, *Linear Integrated Circuits*, New Age Int. Pub., 5th edition.

REFERENCES

- 1. Albert Malvino and Bates J.,2013, *Electronic Principles*, Tata McGraw- Hill Pub. Company Ltd., 7th edition.
- 2. Millman J., Halkias C.C. and SatyabrataJit., 2010, *Electronic Devices and Circuits,* Tata McGraw Hill, New Delhi, 3rd edition.
- 3. Thomas L. Floyd., 2010, *Electronic Devices*, Pearson Education Asia, 9th edition.
- 4. NPTEL Video Lecture Notes on "Analog Electronic Circuits" and "Integrated Circuits, MOSFETs, Op-Amps and their applications.
- 5. Donald A Neaman., 2012 Semiconductor Physics and Devices, Fourth Edition, Tata McGraw Hill Inc.2012.

MT1302 FLUID MECHANICS AND THERMAL SCIENCES

OBJECTIVES

This course enables the students to

- To introduce the basic concepts of fluid mechanics.
- To introduce the applications of the conservation laws to flow through pipes.
- To make students understand the working principle of different types of pumps and Hydraulic turbines.
- To make students understand the basic laws of thermodynamics.
- To introduce various mechanisms of heat transfer

UNIT I PROPERTIES OF FLUIDS

Units and dimensions- Properties of fluids- mass density, specific weight, specific volume, specific gravity, viscosity, compressibility, vapor pressure, surface tension and capillarity. Flow characteristics – Concept of control volume - Application of continuity equation, Energy equation and Momentum equation.

UNIT II FLOW THROUGH CIRCULAR CONDUITS

Hydraulic and energy gradient - Laminar flow through circular conduits and circular annuli-Boundary layer concepts – Types of boundary layer thickness – Darcy Weisbach equation – Friction factor- Moody diagram- Commercial pipes- Minor losses – Flow through pipes in series and parallel - Basics of dimensional analysis.

UNIT III HYDRAULIC MACHINES

Introduction and classification of hydraulic machines - Reciprocating pump: constructional details, working principle, co-efficient of discharge, slip, power required. Centrifugal pump: classification and working principle, specific speed. Turbines: classification, working principle of impulse and reaction turbine.

UNIT IV LAWS OF THERMODYNAMICS

Thermodynamic system and surroundings – Properties of system – State and Equilibrium – Forms of energy – Quasi static process – Zeroth law of thermodynamics – Work and heat transfer – Path and point functions – First law of thermodynamics applied to open systems – SFEE equation and its applications. Second law of thermodynamics applied to Heat engines,

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

9 nc

9

9

Refrigerators & Heat pumps - Carnot's theorem and Clausius inequality – Concept of entropy applied to reversible and irreversible processes – Third law of thermodynamics.

UNIT V HEAT TRANSFER MECHANISMS

Heat transfer mechanisms: Conduction – Fourier's Law, thermal resistance. Convection – Newton's law of cooling. Radiation – Wien's law, Kirchhoff's law, Stefan-Boltzmann law. Heat exchangers – LMTD – NTU – Fins.

TOTAL: 45 PERIODS

9

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO1 Describe the properties of fluids and its importance in selection of fluid for suitable application
- CO2 Identify the major and minor losses involved in the fluid flow through pipes
- CO3 Differentiate the types of hydraulic machines and describe the working principle.
- CO4 Apply the basic laws of thermodynamics for different applications.
- CO5 Distinguish various modes of heat transfer and determine the heat transfer rate.

TEXT BOOKS

- 1. Rajput R.K., 2008, *Heat and Mass transfer*, S.Chand and Co Publishing.
- **2.** Modi PN., Seth SM.,2015, *Hydraulics and fluid mechanics including hydraulic machines*", 20th edition, Standard publishers.

REFERENCES

- Cengel YA., Cimbala J M.,2010, *Fluid Mechanics Fundamentals and applications*, 2nd Edition, McGraw Hill higher education.
- Bansal RK., 2011, Fluid Mechanics and Hydraulics Machines, 9th edition, Laxmi publications (P) Ltd., New Delhi.
- 3. Holman, J.P., 2007, *Heat Transfer*, 3rd Edition, McGraw-Hill.
- 4. White FM., 2011, Fluid Mechanics, 7th Edition, Tata McGraw-Hill, New Delhi.
- 5. Nag P.K., 2005, Engineering thermodynamics, Tata McGraw hill.

MT1303 SOLID MECHANICS

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

OBJECTIVES

This course enables the students to

- To understand the concepts of stress, strain, principal stresses and principal planes.
- To study the concept of shearing force and bending moment due to external loads in determinate beams and their effect on stresses.
- To determine stresses and deformation in circular shafts and helical spring due to torsion.
- To compute slopes and deflections in determinate beams by various methods.
- To study the stresses and deformations induced in thin and thick shells.

UNIT I STRESS AND STRAIN

Stress and strain at a point – Tension, Compression, Shear Stress - Deformation of simple and compound bars – Hooke's Law – Relationship among elastic constants – Stress Strain Diagram for Mild Steel – Ultimate Stress – Yield Stress – Factor of Safety – Thermal Stresses – Thin Cylinders and Shells – Strain Energy due to Axial Force – Resilience – Stresses due to impact and Suddenly Applied Load – Compound Bars.

UNIT II TRANSVERSE LOADING ON BEAMS AND STRESSES IN BEAM 9

Beams – Types transverse loading on beams – Shear force and bending moment in beams– Cantilevers – Simply supported beams and Over – hanging beams - Theory of simple bending–Bending stress distribution – Load carrying capacity – Proportioning of sections – Flitched beams – Shear stress distribution.

UNIT III TORSION

Torsion formulation stresses and Deformation in circular and hollow shafts – Stepped shafts– Deflection in shafts fixed at the both ends – Stresses in helical springs – Deflection of helical springs, carriage springs.

UNIT IV DEFLECTION OF BEAMS

Double integration method – Macaulay's methods – Area moment method – Conjugate beam method for computation of slopes and deflections of determinate beams.

UNIT V THIN CYLINDERS, SPHERES AND THICK CYLINDERS

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

9

9

9

Stresses in thin cylindrical shell due to internal pressure circumferential and longitudinal stresses and Deformation in thin and thick cylinders – Spherical shells subjected to internal pressure – Deformation in spherical shells – Lame's theorem.

TOTAL: 45 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO1 Understand the concepts of stress and strain in simple and compound bars, the importance of principal stresses and principal planes.
- CO2 Understand the load transferring mechanism in beams and stress distribution due to shearing force and bending moment.
- CO3 Apply basic equation of simple torsion in designing of shafts and helical spring
- CO4 Calculate the slope and deflection in beams using different methods.
- CO5 Analyze and design thin and thick shells for the applied internal and external pressures.

TEXT BOOKS

- 1. Bansal, R.K., 2016, Strength of Materials, Laxmi Publications (P) Ltd.
- 2. Jindal U.C., 2009, Strength of Materials Asian Books Pvt. Ltd., New Delhi.

REFERENCES

- 1. Egor. P.Popov, 2002, *Engineering Mechanics of Solids* Prentice Hall of India, New Delhi.
- 2. Ferdinand P. Been, Russell Johnson, J.r. and John J. Dewole, 2005, *Mechanics of Materials*, Tata McGraw Hill Publishing 'co. Ltd., New Delhi.
- 3. Hibbeler, R.C., 2013, *Mechanics of Materials*, Pearson Education, Low Price Edition.
- 4. Subramanian R., 2010, *Strength of Materials*, Oxford University Press, Oxford Higher Education Series.
- 5. Timoshenko Timothy., Strength of Materials, CBS Publishers & Distributors, 2002.

MT1306 ELECTRICAL CIRCUITS AND MACHINES

OBJECTIVES

This course will enable the students to

- To discuss electric circuits and provide knowledge on the analysis of circuits using network theorems
- To understand single and three phase circuits, wiring & working principle of transformer
- To describe the working principle, types, characteristics of DC machines
- To describe the working principle of AC machines
- To explain different types of starters and speed control methods of three phase induction motor & Synchronous motor

UNIT I ELECTRICAL CIRCUITS

Basic circuit components - Ohms Law - Kirchhoff's Law – Instantaneous Power – Inductors - Capacitors – Independent and Dependent Sources - steady state solution of DC circuits - Nodal analysis, Mesh analysis- Thevenin's Theorem, Norton's Theorem, Maximum Power Transfer theorem- Linearity and Superposition Theorem.

UNIT II AC CIRCUITS

Introduction to AC circuits – Waveforms and RMS value – Power and Power factor, Single phase and Three-phase balanced circuits – Three phase loads - House wiring, Industrial wiring, materials of wiring – Principle of Operation of Transformers – EMF Equation of Transformers.

UNIT III DC MACHINES

Types - Constructional details – Principle & operation - Emf equation - Methods of excitation of D.C. generators - Characteristics of series, shunt generator - Principle operation of D.C. motor - Back emf and torque equation - Characteristics of series shunt and Compound motors

UNIT IV AC MACHINES

Constructional details, principle of operation and performance characteristics Single phase induction motor, Three phase induction motor, Synchronous motors.

UNIT V SPEED CONTROL AND STARTING

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

9 70

9

9

9

9

Speed control of D.C. motors – Three phase induction motors - Synchronous motor – starting methods of D.C. motor, Three phase induction motor and Synchronous motor

TOTAL: 45 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO1 Comprehend the basic laws, mesh current, nodal voltage, voltage and current division for solving circuit problems.
- CO2 Solve the networks having DC and AC inputs using network theorems.
- CO3 Select DC Machines for a particular application based on its Characteristics.
- CO4 Select AC Motor for a particular application based on its Characteristics.
- CO5 Differentiate between various types of starting and speed control methods.

TEXTBOOKS

- 1. D P Kothari and I.J Nagarath, *Electrical Machines Basic Electrical and Electronics Engineering*, McGraw Hill Education (India) Private Limited, Third Reprint, 2016.
- Thereja .B.L., Fundamentals of Electrical Engineering and Electronics, S. Chand & Co. Ltd., 2008

REFERENCES

- 1. Del Toro., 2007, Electrical Engineering Fundamentals, Pearson Education, New Delhi.
- 2. John Bird., 2006, *Electrical Circuit Theory and Technology*, Elsevier, First Indian Edition.
- 3. Allan S Moris., 2006, *Measurement and Instrumentation Principles*, Elsevier, First Indian Edition.
- 4. Rajendra Prasad., 2006, *Fundamentals of Electrical Engineering*, Prentice Hall of India.
- 5. A.E.Fitzgerald, David E Higginbotham and Arvin Grabel., 2009, *Basic Electrical Engineering*, McGraw Hill Education(India) Private Limited.
- N K De, Dipu Sarkar., 2016, Basic Electrical Engineering, Universities Press (India) Private Limited

MT1311 SOLID AND FLUID MECHANICS LABORATORY

OBJECTIVES

This course enables the students to

- To study the mechanical properties of materials when subjected to different types of loading.
- To study the effect of hardening and tempering process on materials
- To perform microscopic examination on the hardened and tempered samples
- To verify the principles studied in Fluid Mechanics theory by performing experiments in pumps.
- To verify the principles studied in Fluid Mechanics theory by performing experiments in turbines.

SOLID MECHANICS

LIST OF EXPERIMENTS

- 1. Tension test on a mild steel rod
- 2. Double shear test on Mild steel and Aluminium rods
- 3. Torsion test on mild steel rod
- 4. Impact test on metal specimen
- 5. Hardness test on metals Brinnell and Rockwell Hardness Number
- 6. Deflection test on beams
- 7. Compression test on helical springs
- 8. Strain Measurement using Rosette strain gauge
- 9. Effect of hardening- Improvement in hardness and impact resistance of steels.
- 10. Tempering- Improvement Mechanical properties Comparison
 - (i) Unhardened specimen
 - (ii) Quenched Specimen and
 - (iii) Quenched and tempered specimen.
- 11. Microscopic Examination of
 - (i) Hardened samples and
 - (ii) Hardened and tempered samples.

FLUID MECHANICS

LIST OF EXPERIMENTS

1. Determination of the Coefficient of discharge of given Orifice meter.

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| L | Т | Ρ | С |
|---|---|---|---|
| 0 | 0 | 4 | 2 |

30

30

- 2. Determination of the Coefficient of discharge of given Venturi meter.
- 3. Calculation of the rate of flow using Rota meter.
- 4. Determination of friction factor for a given set of pipes.
- Conducting experiments and drawing the characteristic curves of centrifugal pump/ submergible pump
- 6. Conducting experiments and drawing the characteristic curves of reciprocating pump.
- 7. Conducting experiments and drawing the characteristic curves of Gear pump.
- 8. Conducting experiments and drawing the characteristic curves of Pelton wheel.
- 9. Conducting experiments and drawing the characteristics curves of Francis turbine.
- 10. Conducting experiments and drawing the characteristic curves of Kaplan turbine.

TOTAL: 60 PERIODS

COURSE OUTCOMES

After successful completion of the course, Students will be able to

- CO1 Perform Tension, Torsion, Hardness, Compression, and Deformation test on Solid materials.
- CO2 Perform shear, impact and deflection test.
- CO3 Use the measurement equipments for flow measurement.
- CO4 Perform test on different pump.
- CO5 Perform test on different turbines.

LIST OF EQUIPMENT FOR BATCH OF 30 STUDENTS

| NAME OF THE EQUIPMENT | Qty. |
|--|------|
| Universal Tensile Testing machine with double 1 shear attachment – 40 Ton Capacity | 1 |
| Torsion Testing Machine (60 NM Capacity) | 1 |
| Impact Testing Machine (300 J Capacity) | 1 |
| Brinell Hardness Testing Machine | 1 |
| Rockwell Hardness Testing Machine | 1 |
| Spring Testing Machine for tensile and compressive loads (2500 N) | 1 |
| Metallurgical Microscopes | 3 |
| Muffle Furnace (800 C) | 1 |
| Orifice meter setup | 1 |

| Venturi meter setup | 1 |
|---|---|
| Rotameter setup | 1 |
| Pipe Flow analysis setup | 1 |
| Centrifugal pump/submergible pump setup | 1 |
| Reciprocating pump setup | 1 |
| Gear pump setup | 1 |
| Pelton wheel setup | 1 |
| Francis turbine setup | 1 |
| Kaplan turbine setup | 1 |

MT1316 ELECTRICAL CIRCUITS AND MACHINES LABORATORY

| L | Т | Ρ | С |
|---|---|---|---|
| 0 | 0 | 4 | 2 |

OBJECTIVES

This course enables the students to

- To understand the basic concepts of electrical circuits and associated theorems.
- To understand the fundamentals of DC shunt motors and induction motors.
- To understand the load test and performance characteristics of DC shunt motor, stepper motor and induction motors.
- To give practical exposure to students on various electrical and electronics components.
- To give hands-on practice on design of simple analog circuits.

LIST OF EXPERIMENTS:

- 1. Verification of Ohm's Law & Kirchhoff's Laws.
- 2. Verification of Thevenin theorem
- 3. Verification of Norton's theorem
- 4. Load test on D.C. shunt motor.
- 5. Speed control of D.C. shunt motor.
- 6. Swinburne's test.
- 7. Load test on three phase induction motor.
- 8. No load and blocked rotor tests on three phase induction motor.

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

- 9. Load test on single phase induction motor.
- 10. No load and blocked rotor tests on single phase induction motor.
- 11. Load test on Synchronous motors.
- 12. Performance characteristics of Stepper motor.
- 13. Performance characteristics of Single phase transformer.
- 14. Study of Starters

TOTAL: 60 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO1 Compute the performance of the DC machines for varying load.
- CO2 Compute the performance of single phase & three phase AC motor for varying load.
- CO3 Select suitable speed control method of AC and DC motor.
- CO4 Calculate the performance parameters of stepper motor and transformers
- CO5 Apply basic electrical laws and network theorems for solution of simple DC & AC circuits.

LIST OF EQUIPMENTS FOR A BATCH OF 30 STUDENTS

| NAME OF THE EQUIPMENT | Quantity |
|---------------------------------------|----------|
| Shunt motor 5HP | 3 |
| Single phase Induction Motor 2HP | 2 |
| Three phase induction Motor 5HP | 2 |
| Single phase transformer 2KVA | 1 |
| Three phase auto transformer | 2 |
| Single phase auto transformer | 2 |
| 3 point starter | 3 |
| DPST, TPST Each | 2 |
| DC source 300v, 100A | 1 |
| Ammeter(0-5A),(0-10A)MC Each | 2 |
| Ammeter(0-5A),(0-10A)MI Each | 2 |
| Voltmeter(0-300V) MC | 3 |
| Voltmeter(0-150V),(0-300V),(0-600V)MI | 2 |
| Each | |
| Wattmeter 150/300V, 5/10A UPF | 2 |

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| Wattmeter 300/600V,5/10A UPF | 2 |
|-------------------------------|----|
| Wattmeter 150/300V,5/10A LPF | 2 |
| Wattmeter 300/600V,5/10A LPF | 2 |
| Stepper motor 5Kg | 1 |
| Synchronous motor 5KW | 1 |
| Rheostat 360 ohm/1.2A | 3 |
| Tachometer | 5 |
| Rheostat 50 ohm/5A | 3 |
| Resistors & Breadboards | - |
| Dual Regulated power supplies | 6 |
| Ammeter A.C and D.C | 20 |
| Voltmeters A.C and D.C | 20 |

HS1321 INTERPERSONAL SKILLS- LISTENING AND SPEAKING

OBJECTIVES

The course will enable learners to:

- Equip students with the English language skills required for the successful undertaking of academic studies with primary emphasis on academic speaking and listening skills.
- Provide guidance and practice in basic general and classroom conversation and to engage in specific academic speaking activities.
- improve general and academic listening skills
- Make effective presentations.

Unit I LISTENING AS A KEY SKILL

Listening as a key skill- its importance- speaking – give personal information – ask for personal information – express ability – enquire about ability – ask for clarification - Improving pronunciation– pronunciation basics — stressing syllables and speaking clearly – intonation patterns – conversation starters: small talk.

Unit II LISTEN TO A PROCESS INFORMATION

Listen to a process information- give information, as part of a simple explanation — taking lecture notes – preparing to listen to a lecture – articulate a complete idea as opposed to

| L | Т | Ρ | С |
|---|---|---|---|
| 0 | 0 | 2 | 1 |

6

producing fragmented utterances - compare and contrast information and ideas from multiple sources- converse with reasonable accuracy over a wide range of everyday topics.

Unit III LEXICAL CHUNKING

Lexical chunking for accuracy and fluency- factors influence fluency, deliver a five-minute informal talk – greet – respond to greetings – describe health and symptoms – invite and offer –accept – decline – take leave – listen for and follow the gist- listen for detail

Unit IV GROUP DISCUSSION

Being an active listener: giving verbal and non-verbal feedback – participating in a group discussion – summarizing academic readings and lectures conversational speech listening to and participating in conversations – persuade- negotiate disagreement in group work.

Unit V GROUP & PAIR PRESENTATIONS

Formal and informal talk – listen to follow and respond to explanations, directions and instructions in academic and business contexts – strategies for presentations and interactive communication – group/pair presentations

TOTAL: 30 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to:

- CO1 Develop their communicative competence in English with specific reference to listening
- CO2 Prepare conversation with reasonable accuracy
- CO3 Apply lexical Chunking for accuracy in speaking
- CO4 Demonstrate their ability to communicate effectively in GDs
- CO5 Explain directions and instructions in academic and business contexts

TEXTBOOKS

- 1. Brooks, Margret,2011, *Skills for Success. Listening and Speaking. Level 4*, Oxford University Press, Oxford.
- 2. Richards, C, Jack& David Bholke,2010, *Speak Now Level 3*, Oxford University Press, Oxford.

6

6

REFERENCES

- 1. Bhatnagar, Nitin&MamtaBhatnagar,2010, *Communicative English for Engineers and Professionals,* Pearson, New Delhi.
- 2. Hughes, Glyn & Josephine Moate, 2014, *Practical English Classroom*, Oxford University Press, Oxford.
- 3. Vargo, Mari, 2013, Speak Now Level 4, Oxford University Press, Oxford.
- 4. Richards, C, Jack, 2006, Person to Person (Starter), Oxford University Press, Oxford.
- 5. Ladousse, Gillian Porter, 2014, Role Play. Oxford University Press, Oxford.

WEB RESOURCES

- 1. https://www.cambridge.org/elt/blog/wp-content/uploads/2019/10/Learning-Languagein-Chunks.pdf
- 2. https://english.eagetutor.com/english/628-how-to-greet-your-boss-people-inoffice.html
- 3. https://www.groupdiscussionideas.com/group-discussion-topics-with-answers/
- 4. https://www.bbc.co.uk/worldservice/learningenglish/business/talkingbusiness/unit3pr esentations/1opening.html

SEMESTER IV

MA1402 STATISTICS AND NUMERICAL METHODS

OBJECTIVES

The Course will enable students to

- To make them understand the knowledge of testing of hypothesis for small and large samples.
- To describe the concept of design of experiment to make the judgments in the real life problem.
- To explain the techniques for solving the transcendental equations, system of equations and eigen value problems.
- To introduce the numerical techniques for interpolation in various intervals, differentiation and integration which plays an important role in engineering and technology disciplines.
- To solve the ordinary differential equation with initial conditions.

UNIT I TESTING OF HYPOTHESIS

Sampling distributions -Statistical Hypothesis-Tests for single mean and difference of means of large samples (z-test) and Small samples (t-test) – F-test for variance – Chi square test to test the goodness of fit and independence of attributes

UNIT II DESIGN OF EXPERIMENTS

Basic principles of experimental deign: Completely randomized design – Randomized block design – Latin square design-2² factorial designs.

UNIT III SOLUTION OF EQUATIONS AND EIGENVALUE PROBLEMS

Solution of algebraic and transcendental equations : Fixed point iteration method –Newton Raphson method – Solution of linear system of equations: Gauss elimination and Gauss Jordan methods - Iterative methods: Gauss Jacobi and Gauss Seidel – Eigenvalues of a matrix by Power method and Jacobi's method for symmetric matrices.

UNIT IV INTERPOLATION, NUMERICAL DIFFERENTIATION AND NUMERICAL INTEGRATION 12

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 1 | 0 | 4 |

12

12

Interpolation-Lagrange's and Newton's divided difference interpolations for unequal intervals – Newton's forward and backward difference interpolation for equal intervals– Approximation of derivates using interpolation polynomials – Numerical Solution of single and double integrations using Trapezoidal and Simpson's 1/3 rules.

UNIT V NUMERICAL SOLUTION OF ORDINARY DIFFERENTIAL EQUATIONS 12

Single step methods : Taylor series method, Euler's method , Modified Euler's method and Fourth order Runge-Kutta method for solving first order equations – Multi step methods : Milne's and Adam –Bashforth predictor corrector methods for solving first order equations.

TOTAL: 60 PERIODS

COURSE OUTCOMES

After completing this course, students will be able to:

- CO 1 Apply the concept of testing of hypothesis for small and large samples in real life problems.
- CO 2 Apply the basic concepts of classifications of design of experiments.
- CO 3 Apply the techniques for solving the transcendental equations, system of equations and eigen value problems.
- CO 4 Apply the numerical techniques of differentiation and integration for engineering problems.
- CO 5 Solve the ordinary differential equations with initial conditions by various Methods.

TEXT BOOKS

- 1. Johnson, R A, Miller, I, & Freund, J E 2015, *Miller & Freund's Probability and Statistics for Engineers*, 8th Edition, Pearson Education, Asia.
- 2. Grewal, B S, & Grewal, J S 2016, *Numerical Methods in Engineering and Science,* 10th Edition Reprint, Khanna Publishers, New Delhi, India.

REFERENCES

- 1. Walpole, R E, Myers, R H, Myers, S L, & Ye, K 2007, *Probability and Statistics for Engineers and Scientists*, 8th Edition, Pearson Education, Asia.
- 2. Gupta, S C, & Kapoor, V K 2020, *Fundamentals of Mathematical Statistics*, 12th Edition Reprint, Sultan Chand & Sons.
- Sankar Rao, K 2018, Numerical Methods for Scientists and Engineers, 4th Edition, Prentice Hall of India Private.

- 4. Kandasamy, P, Thilagavathy, K, & Gunavathy, K 2014, *Numerical Methods*, 3rd Edition Reprint, S. Chand & Co. Ltd., New Delhi.
- 5. Gerald, C F, & Wheatley, P O 2007, *Applied Numerical Analysis,* 7th Edition, Pearson Education, Asia, New Delhi.

WEB REFERENCES

- 1. https://fac.ksu.edu.sa/sites/default/files/probability_and_statistics_for_engineering _and_the_sciences.pdf
- 2. http://www.elcom-hu.com/Mshtrk/Statstics/9th%20txt%20book.pdf
- 3. https://fac.ksu.edu.sa/sites/default/files/numerical_analysis_9th.pdf

EE1471 CONTROL SYSTEMS ENGINEERING

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

9

9

9

OBJECTIVES

This course enables the students to

- To introduce the components and their representation of control systems
- To learn various methods for analyzing the time response, frequency response and stability of the systems.
- To learn the various approaches for the state variable analysis.

UNIT I SYSTEMS COMPONENTS AND THEIR REPRESENTATION

Control System: Terminology and Basic Structure-Feed forward and Feedback control theory Electrical and Mechanical Transfer Function Models-Block diagram Models-Signal flow graphs models-DC and AC servo Systems-Synchros -Multivariable control system

UNIT II TIME RESPONSE ANALYSIS

Standard Inputs - Transient response & Steady state response - Measures of performance of the standard first order and second order system - Effect on an additional zero and an additional pole- Steady error constant and system type number -PID control - Analytical design for PD, PI,PID control systems

UNIT III FREQUENCY RESPONSE AND SYSTEM ANALYSIS

Closed loop frequency response-Performance specification in frequency domain-Frequency response of standard second order system- Bode Plot - Polar Plot- Design of compensators using Bode plots-Cascade lead compensation-Cascade lag compensation-Cascade lag-lead

compensation

UNIT IV CONCEPTS OF STABILITY ANALYSIS

Concept of stability-Bounded - Input Bounded - Output stability-Routh stability criterion-Relative stability-Root locus concept-Guidelines for sketching root locus-Nyquist stability criterion.

UNIT V CONTROL SYSTEM ANALYSIS USING STATE VARIABLE METHODS 9

State variable representation-Conversion of state variable models to transfer functions-Conversion of transfer functions to state variable models-Solution of state equations-Concepts of Controllability and Observability-Stability of linear systems-Equivalence between transfer function and state variable representations-State variable analysis of digital control system-Digital control design using state feedback.

TOTAL: 45 PERIODS

9

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO1 Identify the various control system components and their representations.
- CO2 Analyze the various time domain parameters.
- CO3 Analysis the various frequency response plots and its system.
- CO4 Apply the concepts of various system stability criterions.
- CO5 Design various transfer functions of digital control system using state variable models

TEXT BOOK

1. M.Gopal., 2012, *Control System – Principles and Design*, Tata McGraw Hill, 4th Edition.

REFERENCES

- 1. J.Nagrath and M.Gopal, 2007, *Control System Engineering*, New Age International Publishers, 5 th Edition.
- 2. K. Ogata., 2012, Modern Control Engineering, 5th edition, PHI.
- 3. S.K.Bhattacharya., 2013, Control System Engineering, 3rd Edition, Pearson.
- 4. Benjamin.C.Kuo.,1995, Automatic control systems II, Prentice Hall of India, 7th Edition

ME1471 KINEMATICS OF MACHINERY

OBJECTIVES

This course enables the students to

- To understand the basic components and layout of linkages in the assembly of a system machine.
- To understand the principles in analyzing the assembly with respect to the displacement, velocity, and acceleration at any point in a link of a mechanism.
- To understand the motion resulting from a specified set of linkages, design few linkage mechanisms and cam mechanisms for specified output motions.
- To understand the basic concepts of toothed gearing and kinematics of gear trains and the effects of friction in motion transmission and in machine components

UNIT I BASICS OF MECHANISMS

Classification of mechanisms – Basic kinematic concepts and definitions – Degree of freedom, Mobility – Kutzbach criterion, Gruebler's criterion – Grashof's Law – Kinematic inversions of four bar chain and slider crank chains – Limit positions – Mechanical advantage – Transmission Angle – Description of some common mechanisms – Quick return mechanisms, Straight line generators, Universal Joint – rocker mechanisms.

UNIT II KINEMATICS OF LINKAGE MECHANISMS

Displacement, velocity and acceleration analysis of simple mechanisms – Graphical method– Velocity and acceleration polygons – Velocity analysis using instantaneous centres – Kinematic analysis of simple mechanisms – Coincident points – Coriolis component of Acceleration – Introduction to linkage synthesis problem.

UNIT III KINEMATICS OF CAM MECHANISMS

Classification of cams and followers – Terminology and definitions – Displacement diagrams – Uniform velocity, parabolic, simple harmonic and Cycloidal motions – Derivatives of follower motions – Layout of plate cam profiles – Specified contour cams – Circular arc and tangent cams – Pressure angle and undercutting – sizing of cams

UNIT IV GEARS AND GEAR TRAINS

Law of toothed gearing – Involutes and Cycloidal tooth profiles – Spur Gear terminology and definitions –Gear tooth action – Contact ratio – Interference and undercutting. Helical, Bevel,

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

9

9

9

9

Worm, Rack and Pinion gears [Basics only]. Gear trains – Speed ratio, train value – Parallel axis gear trains – Epicyclic Gear Trains.

UNIT V FRICTION IN MACHINE ELEMENTS

Surface contacts – Sliding and Rolling friction – Friction in Plate clutches – Axial clutches – Cone Clutches-Internal expanding rim clutches – Electromagnetic clutches. Friction in Band and Block brakes – External shoe brakes – Internal expanding shoe brake

TOTAL: 45 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO1 Define various components of mechanisms and explain the various inversions of a mechanism
- CO2 Illustrate the kinematic linkages with respect to displacement, velocity, and acceleration at any point
- CO3 Design cam profile for specified follower motions
- CO4 Demonstrate the basic concepts of toothed gearing and the kinematics of gear trains
- CO5 Compute the frictional forces in various power transmission systems such as Clutches and Brakes

TEXT BOOKS

- 1. Rattan, S.S, 2014, *Theory of Machines*,4thEdition, Tata McGraw-Hill.
- 2. F.B.Sayyad, 2011, *Kinematics of Machinery*. MacMillan Publichers Pvt Ltd., Techmax Educational resources.
- 3. Uicker J.J., 2014, Pennock G.R and Shigley, J.E., *Theory of Machines and Mechanisms*,4th Edition, Oxford University Press.

REFERENCES

- 1. Khurmi, R.S., 2005, Theory of Machines, 14 Edition, S Chand Publications.
- 2. Allen S.Hall Jr., 1961, Kinematics and Linkage design, Prentice Hall.
- 3. Thomas Bevan, 2005, *Theory of Machines*, 3rd Edition, CBS Publishers and Distributors.
- 4. Robert L. Norton, 2009, Kinematics and Dynamics of Machinery, Tata McGraw-Hill

MT1401

OBJECTIVES

This course enables the students to

- To understand the basic concepts of sand-casting technique and special casting technique.
- To know the principles, equipment's of different welding techniques.
- To understand the basic concepts and working of Traditional machining process.
- To know the basic concepts and working of Non-traditional machining process.
- To understand the working principles of different types of Metal forming and Plastic manufacturing methods.

UNIT I METAL CASTING PROCESSES

Casting types, procedure to make sand mould, types of core making, moulding tools, machine moulding - melting furnaces: Blast and Cupola Furnaces;

Special moulding processes – CO₂ moulding, Shell moulding, Investment moulding, Permanent mould casting, Pressure die-casting, Centrifugal casting, Continuous casting – Stir casting – Casting defects.

UNIT II METAL JOINING PROCESSES

Classification of Welding processes- Principles of Oxy-acetylene gas welding - A.C metal arc welding, Resistance welding, Submerged arc welding, Tungsten inert gas welding, Metal inert gas welding - Plasma arc welding - Thermit welding- Electron beam welding- Laser beam welding- Friction welding and friction stir welding -Soldering and brazing- Defects in welding.

UNIT III CONVENTIONAL MACHINING PROCESSES

General principles, working and operations of: Lathe, Shaper, Planer, Milling machines, Drilling machine - Gear generation methods - Broaching machines – Cylindrical grinding, Surface grinding, Centreless grinding and Internal grinding – Introduction to CNC Machining.

UNIT IV UNCONVENTIONAL MACHINING PROCESSES

General principles, working and applications of: Water jet machining, Abrasive jet machining, Ultrasonic machining, Electric discharge machining, Electro chemical machining, Plasma arc machining, Electron beam machining, Laser beam machining, Chemo-mechanical polishing,

9

9

9

Magneto rheological finishing. Comparison of Conventional & Unconventional machining processes.

METAL FORMING AND MANUFACTURING OF PLASTIC

COMPONENTS

9

Principles and applications: Forging, Rolling, Extrusion, Wire drawing, Spinning, HERF Process - Powder metallurgy

Types of plastics – Moulding of Thermoplastics – Injection moulding– Blow moulding – Rotational moulding – Film blowing – Extrusion – Thermoforming – Processing of Thermosets –Compression moulding – Transfer moulding – Bonding of Thermoplastics.

TOTAL: 45 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to

- CO 1 Identify and Select suitable casting process for a specific component
- CO 2 Explain the working principles and applications of different arc welding processes, special welding process and defects associated with it
- CO 3 Select the suitable process for manufacturing of components using suitable conventional machining
- CO 4 Select the suitable process for manufacturing of components using suitable unconventional machining
- CO 5 Understand various metal forming process and manufacturing methods of plastic components

TEXT BOOKS

- 1. Hajra Choudhary. S.K and Hajra Choudhary. A.K., 2010, *Elements of Workshop Technology*, volume I and II, Media Promoters and Publishers Private Limited, Mumbai.
- 2. Kalpakjian. S, 2018, *Manufacturing Engineering and Technology*, 7th Edition, Pearson Education India Edition.

REFERENCES

- 1. *H.M.T. Production Technology Handbook*, Tata McGraw-Hill, 2000.
- 2. Roy A. Lindberg, 2006, *Processes and Materials of Manufacture*, PHI / Pearson education.
- 3. Black J.T and Ronald A. Kosher, 2017, *Degarmos Materials and Processes, in Manufacturing* 12th Edition, Wiley Publishers.

- 4. Sharma, P.C., 2006, A Text book of production Technology, S.Chand and Co. Ltd.
- 5. Adithan. M and Gupta. A.B., 2006, *Manufacturing Technology*, New Age.

MT1402 MICROPROCESSORS AND ITS APPLICATIONS

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

OBJECTIVES

- Understand fundamental operating concepts behind microprocessors and microcontrollers.
- Emphasis on the hardware features of Microprocessor 8085 and Microcontroller 8051 with their functions
- To apply instructions and addressing modes and write programs using 8085
- Understand commonly used peripheral / interfacing
- To apply instructions and algorithms write programs using 8051.

UNIT I 8085 PROCESSOR

Hardware Architecture, pin diagram – Functional Building Blocks of Processor – Memory organization – I/O ports and data transfer concepts– Timing Diagram – Interrupts.

UNIT II PROGRAMMING OF 8085 PROCESSOR

Instruction - format and addressing modes – Assembly language format – Data transfer, data manipulation& control instructions – Programming: Loop structure with counting & Indexing – Look up table - Subroutine instructions - stack.

UNIT III 8051 MICRO CONTROLLER

Hardware Architecture, pin diagram – Functional Building Blocks of Processor – Memory organization – I/O ports and data transfer concepts– Serial Communication – Interrupts-Introduction to Arduino & Raspberry pi.

UNIT IV PERIPHERAL INTERFACING

Introduction on Architecture, configuration and interfacing, with ICs: 8255, 8259, 8254,8237,8251, 8279 - A/D and D/A converters.

UNIT V MICRO CONTROLLER PROGRAMMING & APPLICATIONS

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

9

9

9

9

Data Transfer, Manipulation, Control Algorithms& I/O instructions – Simple programming exercises-key board and display interface – Closed loop control of servo motor- stepper motor control – Washing Machine Control.

TOTAL: 45 PERIODS

TEXT BOOKS

- 1. Krishna Kant., 2013, *Microprocessor and Microcontrollers*, Eastern Company Edition, Prentice Hall of India, New Delhi.
- 2. Muhammad Ali Mazidi & Janice Gilli Mazidi, R.D.Kinely., 2007, *The 8051 Micro Controller and Embedded Systems*, PHI Pearson Education, 5th Indian reprint.

REFERENCES

- 1. N.Senthil Kumar, M.Saravanan, S.Jeevananthan., 2016, *Microprocessors and Microcontrollers*, Oxford.
- 2. Soumitra Kumar Mandal., 2013, *Microprocessor & Microcontroller Architecture, Programming & Interfacing using 8085,8086,8051*,McGraw Hill Edu.
- 3. Valder Perez., 2013, *Microcontroller Fundamentals and Applications with Pic,* Yeesdee Publishers, Tayler & Francis.
- 4. R.S. Gaonkar., 2013, *Microprocessor Architecture Programming and Application, with 8085*, Wiley Eastern Ltd., New Delhi.

MT1403 SENSORS AND INSTRUMENTATION

| L | Т | Ρ | С |
|---|---|---|---|
| 3 | 0 | 0 | 3 |

OBJECTIVES

This course enables the students to

- To understand the concepts of measurement technology and various transducers, sensors.
- To know about the different motion, proximity, ranging sensors.
- To learn the various sensors used to measure various physical and optical parameters.

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

- To acquire knowledge on various Pressure, Temperature and advanced sensors.
- To learn the fundamentals of signal conditioning, data acquisition and communication systems used in mechatronics system development.

UNIT I INTRODUCTION

Basics of Measurement Units and Standards– Classification of sensors –Contact and Non Contact Sensors- Classification of errors – Error analysis – Static and dynamic characteristics of transducers – Performance measures of sensors —Sensor calibration techniques – Sensor Output Signal Types –Wiring Techniques- specifications and manufacturer of sensors

UNIT II MOTION, PROXIMITY AND RANGING SENSORS

Motion Sensors – Potentiometers, Resolver, Encoders – Optical, Magnetic, Inductive, Capacitive, LVDT – RVDT – Synchro – Microsyn, Accelerometer – GPS, Bluetooth, Range Sensors – RF beacons, Ultrasonic Ranging, Reflective beacons, Laser Range Sensor (LIDAR).

UNIT III FORCE, MAGNETIC, HEADING AND OPTICAL SENSORS

Strain Gage, Load Cell, and Magnetic Sensors –types, principle, requirement and advantages: Magneto resistive – Hall Effect – Current sensor Heading Sensors – Compass, Gyroscope, Inclinometers - Photo conductive cell, photo voltaic, Photo resistive, LDR – Fiber optic sensors

UNIT IV PRESSURE TEMPERATURE AND ADVANCED SENSORS 9

Pressure –Diaphragm, Bellows, Piezoelectric – Tactile sensors, Temperature – IC, Thermistor, RTD, Thermocouple. Acoustic Sensors – flow and level measurement, Radiation Sensors - Smart Sensors - Film sensor, MEMS & Nano Sensors, LASER sensors.

UNIT V SIGNAL CONDITIONING AND DAQ SYSTEMS

Amplification – Filtering – Sample and Hold circuits – Data Acquisition: Single channel and multichannel data acquisition – Data logging - applications - Automobile, Aerospace, Home appliances, Manufacturing, Environmental monitoring.

TOTAL: 45 PERIODS

9

9

9

COURSE OUTCOMES:

After successful completion of the course, the students will be able to

- CO1 Outline the various calibration techniques and types of sensors and transducers
- CO2 Summarize the various sensors used in the Motion and Ranging applications
- CO3 Describe the working principle and characteristics of force, magnetic , heading and optical sensors
- CO4 Understand the basic principles of various pressure and temperature, smart sensors
- CO5 Ability to implement the DAQ systems with different sensors for real time applications

TEXT BOOKS

- 1. Ernest O Doebelin., 2009, *Measurement Systems Applications and Design*, Tata McGraw-Hill.
- 2. Sawney A K and Puneet Sawney., 2013, *A Course in Mechanical Measurements and Instrumentation and Control*, 12th edition, Dhanpat Rai & Co, New Delhi.

REFERENCES

- C. Sujatha Dyer, S.A., 2001, Survey of Instrumentation and Measurement, John Wiley & Sons, Canada.
- 2. Hans Kurt Tönshoff (Editor), Ichiro., 2001, Sensors in Manufacturing Volume 1, Wiley-VCH April.
- 3. John Turner and Martyn Hill., 1999, *Instrumentation for Engineers and Scientists*, Oxford Science Publications.
- 4. Patranabis D., 2011, Sensors and Transducers, 2nd Edition, PHI, New Delhi.
- 5. Richard Zurawski., 2015, Industrial Communication Technology Handbook 2nd edition, CRC Press.

MT1411 MANUFACTURING TECHNOLOGY AND SENSORS LABORATORY

OBJECTIVES

This course enables the students to

- To demonstrate and study about various machines
- To understand the machine capabilities and processes
- To provide knowledge about sensors.
- To provide knowledge about actuators.
- To provide hands on experience to measure different signal using sensor and processing them in required form.

LIST OF EXPERIMENTS

MANUFACTURING TECHNOLOGY LABORATORY

1. LATHE PRACTICE

- a. Plain Turning
- b. Taper Turning
- c. Thread Cutting

Estimation of machining time for the above turning processes.

2. DRILLING PRACTICE

- a. Drilling
- b. Tapping
- c. Reaming.

3. MILLING

- a. Surface Milling.
- b. Gear Cutting.
- c. Contour Milling.

4. PLANNING AND SHAPING

- a. Cutting Key Ways.
- b. Dovetail machining.

SENSORS LABORATORY

- 1. Design and testing of Digital Comparator
- 2. Design and testing of Voltage to frequency converter and frequency to voltage converter.

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| L | Т | Ρ | С | |
|---|---|---|---|--|
| 0 | 0 | 4 | 2 | |

(30 Hours)

(30 Hours)

- 3. Design and testing of sample and hold circuit.
- 4. Design and testing of Flash type Analog to Digital Converters.
- 5. Design and testing of instrumentation amplifier using OP-AMP.
- 6. Displacement measurement using potentiometer and LVDT and plotting the characteristic curves.
- 7. Study of Characteristics and calibration of strain gauge and Load Cell
- 8. Temperature measurement using Thermocouple, Thermistor and RTD and comparing the characteristics.
- 9. Temperature Measurement using MultiSIM Live Software
- 10. Measurement of sound using microphones and sound level meter.
- 11. Conversation of time domain audio signal into frequency domain signal (FFT).
- 12. Study of Temperature & Pressure Transmitter

TOTAL: 60 PERIODS

COURSE OUTCOMES

After successful completion of the course, the students will be able to:

- CO1 Utilize different machine tools for manufacturing gears
- CO2 Utilize different machine tools for finishing operations.
- CO3 Generate appropriate design procedure, suitable for signal conversion to interface with computer.
- CO4 Design appropriate circuits by using conventional formulas used in signal conditioning and conversion.
- CO5 Generate appropriate design procedure to obtain a required measurement data for temperature, force, humidity, displacement and sound.

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

| NAME OF THE EQUIPMENT | Qty. |
|-----------------------------|--------|
| Lathe | 15 No. |
| Drilling Machine | 1 No. |
| Milling Machine | 2 No. |
| Planning Machine | 1 No. |
| Shaping Machine | 2 No. |
| Digital Signal Oscilloscope | 6 No. |

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

| Function Generator | 5 No. |
|--|--------|
| Breadboard | 10 No. |
| Regulated Power supply | 6 No. |
| LVDT | 1 No. |
| Thermistor | 1 No. |
| Thermocouple | 1 No. |
| RTD | 1 No. |
| Load cell setup | 1 No. |
| 4 Channel data acquisition system for strain gauge | 1 No. |
| Sound level meter | 1 No. |
| Computer with LABVIEW/ MATLAB/SCILAB | 1 No. |
| Prony brake dynamometer | 1 No. |
| Hygrometer | 1 No. |
| | |

MT1412 MICROPROCESSORS AND ITS APPLICATIONS LABORATORY

OBJECTIVES

This course enables the students to

- To focus on the implementation of arithmetic operations using microprocessors
- To focus on the implementation of arithmetic operations using microcontrollers
- To simulate assembly language programs.
- To implement various on-chip and off-chip interfacing and algorithms
- To develop mini projects using processors

LIST OF EXPERIMENTS

- 1. Simple arithmetic operations: addition / subtraction / multiplication / division.
- 2. Programming with control instructions
 - i. Ascending / Descending order, Maximum / Minimum of numbers
 - ii. Programs using Rotate instructions.
 - iii. Hex / ASCII / BCD code conversions
- 3. Interface Experiments: with 8085
 - i. A/D Interfacing & (ii) D/A Interfacing.
- 4. Traffic light controller

39

Т

0

L

0

Ρ

4

С

- 5. I/O Port / Serial communication
- 6. Programming Practices with Simulators/Emulators/open source
- 7. Read a key interface display
- 8. Demonstration of basic instructions with 8051 Micro controller execution, including:
 - i. Conditional jumps, looping ii) Calling subroutines
- 9. Programming I/O Port 8051
 - i. study on interface with A/D & D/A
 - ii. study on interface with DC & AC motor
- 10. Mini project development with processors

TOTAL: 60 PERIODS

COURSE OUTCOMES:

At the end of the course, students will be able to

- CO1 Apply the concepts of partial derivatives to find the higher derivatives of multi variable functions.
- CO2 Apply the techniques of multi variable calculus to compute the gradients, directional derivative and extreme values
- CO3 Test the given system of equation is linearly dependent or independent.
- CO4 Apply the concept of eigen values and eigenvectors for Diagonalization of a matrix
- CO5 Apply the inner product techniques for finding the orthonormal vector and minimal solution to the system of linear equation

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS:

| Description of Equipment | Quantity required |
|---|-------------------|
| 8085 Microprocessor Trainer with Power Supply | 15nos |
| 8051 Micro Controller Trainer Kit with power supply | 15nos |
| 8255 Interface board | 5nos |
| 8251 Interface board | 5nos |
| 8259 Interface board | 5nos |
| 8279 Keyboard / Display Interface board | 5nos |
| 8254 timer counter | 5nos |
| ADC and DAC card | 5nos |
| AC & DC motor with Controller | 5nos |
| Traffic Light Control System | 5nos |

Curriculum and Syllabi | B.E Mechatronics Engineering | R2020

HS1421 AN INTRODUCTION TO ADVANCED READING AND WRITING

OBJECTIVES

The Course will enable learners to:

- To strengthen the reading skills of students of engineering.
- To enhance their writing skills with specific reference to technical writing
- To develop their critical thinking skills.
- To provide more opportunities to develop their project and proposal writing skills

UNIT I EFFECTIVE READING

Reading – Strategies for effective reading-Use glosses and footnotes to aid reading comprehension- Read and recognize different text types-Predicting content using photos and title. Reading-Read for details-Use of graphic organizers to review and aid comprehension.

UNIT II CRITICAL READING

Reading– Understanding pronoun reference and use of connectors in a passage- speed reading techniques. Reading– Genre and Organization of Ideas- Reading– Critical reading and thinking- understanding how the text positions the reader.

UNIT III PARAGRAPH WRITING

Writing-Plan before writing- Develop a paragraph: topic sentence, supporting sentences, concluding sentence. Write a descriptive paragraph Writing-State reasons and examples to support ideas in writing– Write a paragraph with reasons and examples- Write an opinion paragraph

UNIT IV ESSAY WRITING

Writing– Elements of a good essay-Types of essays- descriptive-narrative- issue-basedargumentative-analytical.

UNIT V EFFECTIVE WRITING

Writing– Email writing- visumes – Job application- Report Writing - Project writing-Writing convincing proposals

TOTAL: 30 PERIODS

L T P C 0 0 2 1

6

6

6

6

41

COURSE OUTCOMES

- CO1 Understand how the text positions the reader
- CO2 Develop critical thinking while reading a text
- CO3 Develop a descriptive paragraph
- CO4 Make use of sentence structures effectively when creating an essay
- CO5 Demonstrate proper usage of grammar in writing E-Mails, Job application and project proposals

TEXT BOOKS

- 1. Gramer, F, Margot & Colin, S, Ward, 2011, *Reading and Writing (Level 3)* Oxford University Press, Oxford.
- 2. Debra Daise, CharlNorloff, and Paul Carne, 2011, *Reading and Writing (Level 4)* Oxford University Press: Oxford.

REFERENCES

- 1. Davis, Jason & Rhonda LIss. *Effective Academic Writing (Level 3)* Oxford University Press: Oxford, 2006
- 2. E. Suresh Kumar and et al. *Enriching Speaking and Writing Skills*. Second Edition. 2012, Orient Black swan:Hyderabad.
- 3. Withrow, Jeans and et al. *Inspired to Write. Readings and Tasks to develop writing skills.* 2004, Cambridge University Press: Cambridge.
- 4. Goatly, Andrew. *Critical Reading and Writing*, 2000, Routledge: United States of America.
- 5. Petelin, Roslyn & Marsh Durham, *The Professional Writing Guide: Knowing Well and Knowing Why*, 2004, Business & Professional Publishing: Australia.

WEB RESOURCES

- 1. http://learnenglishteens.britishcouncil.org/skills/reading
- 2. https://learnenglish.britishcouncil.org/skills/reading
- 3. https://www.readingrockets.org/article/25-activities-reading-and-writing-fun
- 4. https://linguapress.com/advanced.html